



# MSD Servodrive

Specification

CANopen

+ 2 analog outputs





# MSD Servodrive Specification

# CANOP⊗∩ + 2AO for MSD Servodrive

Id.-No.: CA79904-001

Rev. 1.0 1109

Applicable as from firmware version: V1.1



This document does not replace the MSD Servodrive Operation Manual. Please be sure to observe the information contained in the "For your safety", "Intended use" and "Responsibility" sections of the Operation Manual (ID no.: CA65642-001). For information on installation, setup and commissioning, and details of the warranted technical characteristics of the MSD Servodrive series, refer to the additional documentation (Operation Manual, User Manual, etc.).

## Technical alterations reserved.

The contents of our documentation have been compiled with greatest care and in compliance with our present status of information.

Nevertheless we would like to point out that this document cannot always be updated parallel to the technical further development of our products.

Information and specifications may be changed at any time. For information on the latest version please refer to drives-support@moog.com.



Note: This specification relates solely to the function of the two analog outputs OEA00 and OEA01.

The interconnection concept for the CANopen bus system is not detailed in this document. A detailed description of the interconnection of a MSD Servodrive with the CANopen bus system is given in the

"User Manual CANopen / EtherCAT (ID no.: CA65647-001).

# 1. Analog outputs

This document specifies the functions and features of the analog outputs communication option (Opt 1). The two analog outputs enable a selectable actual value (see table 1.1) to be obtained from the controller. The analog value can be transmitted to a display unit, or be made available for further processing.

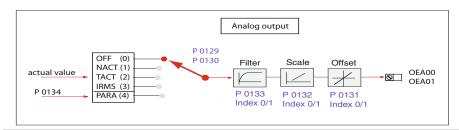


Figure 1.1 Analog outputs schematic

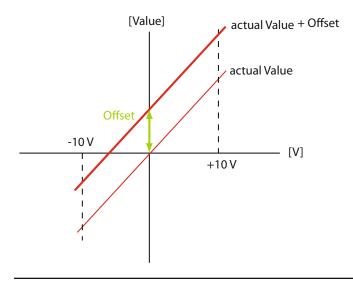


Figure 1.2 Offset function: Shift output by one variable

#### Settings:

Number	Setting	MDA 5 display	Function
P 0129 P 0130	(0) OFF	No function	No function
	(1) NACT	Actual speed	Output of actual speed
	(2) TACT	Actual torque/force	Output of torque/force
	(3) IRMS	RMS current	Output of mean current
	(4) PARA PARA	DADA	PARA delivers a defined value (see P 0134) at the
		TAKA	analog output
P 0134	-10 V to +10 V	Value of analog outputs by parameter	Setting to test the analog output.

Table 1.1 Selection of actual value variable for output





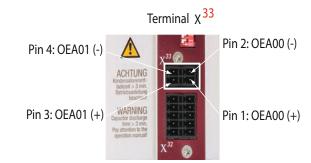
#### Technical data:

Technical data	Analog outputs OAE00 / OAE01
Number of channels	2 channels
Resolution Accuracy	12 Bit max. +/- 2 % referred to 10 V offset error: < +/- 0,1 V
Specified output voltage Max. voltage	+/- 10 V, differential U <sub>max</sub> : +/- 12,5 V
Max. output current Capacitive load	<ul> <li>5,0 mA at 10 V, short-circuit-proof (1)(2)</li> <li>Capacitance: max. 5 nF: Cable length max. approx. 25 m</li> </ul>
Update cycle	Corresponding to the clock frequency of the power stage (default 8 KHz)

Table 1.2 Technical data

- <sup>(1)</sup> An output is essentially short-circuit-proof. However, both outputs must not be shorted for longer than 60 seconds.
- $^{(2)}$  To avoid electromagnetic interference, the connected evaluation electronics should be high-resistance (  $> 20 \text{ k}\Omega$ ) against PE and DGND (Digital Ground).

### 1.1 Connections



Pin 1	Analog output OEA00 (+)	
Pin 2	Analog output OEA00 (-)	
Pin 3	Analog output OEA01 (+)	
Pin 4	Analog output OEA01 (-)	

Figure 1.3 Terminal assignment

## 1.2 Operator control and parameter setting

The output variables are selected, offset, scaled and filtered by the following parameters. They are to be found in the subject area: "I/O configuration - analog outputs".

#### "Offset"

P0131	Setting	Description
0 OEA00	max +10 V / min -10 V	Any variation of the voltage value can be adjusted
1 OEA01	max +10 V / min -10 V	by an offset.

Table 1.3 Setting of the voltage offset

#### "Scale"

P0132	Setting	Description
0 OEA00	Value in V/dim	Scaling of the analog output. The output can be
1 OEA01	Value in V/dim	adjusted to the dimension currently being applied. <sup>(1)</sup>

Table 1.4 Scaling of the analog output

(1) Formula to determine the scaling value Parameter P 0132 Scale:

Formula:	Example:
Scale = $\frac{10 \text{ V}}{\text{Output value}_{\text{maximum}}}$	Scale = $\frac{10 \text{ V}}{3000 \text{ rpm}}$ $Scale = 0,0033 \frac{\text{V}}{\text{rpm}}$

### "Filter"

P01333	Setting	Description
0 OEA00	Value in ms	Catting of filter time for pains suppression
1 OEA01	Value in ms	Setting of filter time for noise suppression.

Table 1.5 Filter of output value



MOOG GmbH Hanns-Klemm-Straße 28 D-71034 Böblingen Phone +49 7031 622 0 Fax +49 7031 622 100

www.moog.com/industrial drives-support@moog.com

Moog is a registered trademark of Moog, Inc. and ist subsidiaries.
All quoted trademarks are the property of Moog, Inc. and its subsidiaries.
All rights reserved.

© 2009 Moog GmbH

### Technical alterations reserved.

The contents of our documentation have been compiled with greatest care and in compliance with our present status of information.

Nevertheless we would like to point out that this document cannot always be updated parallel to the technical further development of our products.

Information and specifications may be changed at any time. For information on the latest version please refer to drives-support@ moog.com.

Id.-No.: CA79904-001 Rev. 1.0, 1109